

Understanding Random SAT

Beyond the Clauses-to-Variables Ratio

Eugene Nudelman
Stanford University

joint work with...

Kevin Leyton-Brown

Holger Hoos


University of British Columbia

Alex Devkar

Yoav Shoham

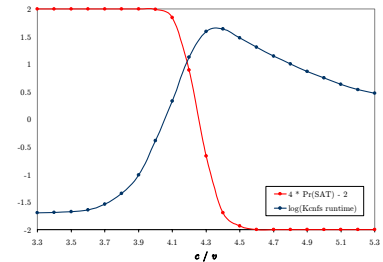
Stanford University

Introduction

- SAT is one of the **most studied** problems in CS
- Lots known about its **worst-case** complexity
 - But often, particular instances of \mathcal{NP} -hard problems like SAT are **easy in practice**
- “Drosophila” for **average-case** and **empirical** (typical-case) complexity studies 
- (Uniformly) random SAT provides a way to bridge analytical and empirical work

Previously...

- **Easy-hard-less hard** transitions discovered in the behaviour of DPLL-type solvers [Selman, Mitchell, Levesque]
 - Strongly correlated with phase transition in solvability
 - Spawned a new enthusiasm for using empirical methods to study algorithm performance
- Follow up included study of:
 - Islands of tractability [Kolaitis et. al.]
 - SLS search space topologies [Frank et.al., Hoos]
 - Backbones [Monasson et.al., Walsh and Slaney]
 - Backdoors [Williams et. al.]
 - Random restarts [Gomes et. al.]
 - Restart policies [Horvitz et.al, Ruan et.al.]
 - ...



Empirical Hardness Models

- We proposed building **regression models** as a disciplined way of predicting and studying algorithms' behaviour

[Leyton-Brown, Nudelman, Shoham, CP-02]

- **Applications** of this machine learning approach:

- 1) Predict running time

- Useful to know **how long** an algorithm will run

- 2) Gain theoretical understanding

- Which variables are **important** to the hardness model?

- 3) Build algorithm portfolios

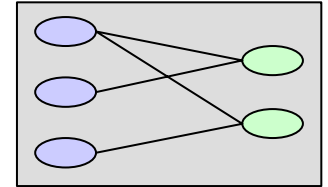
- Can select the right algorithm on a **per-instance** basis

- 4) Tune distributions for hardness

- Can generate **harder** benchmarks by rejecting easy instances

Outline

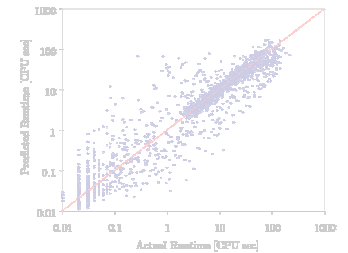
- **Features**



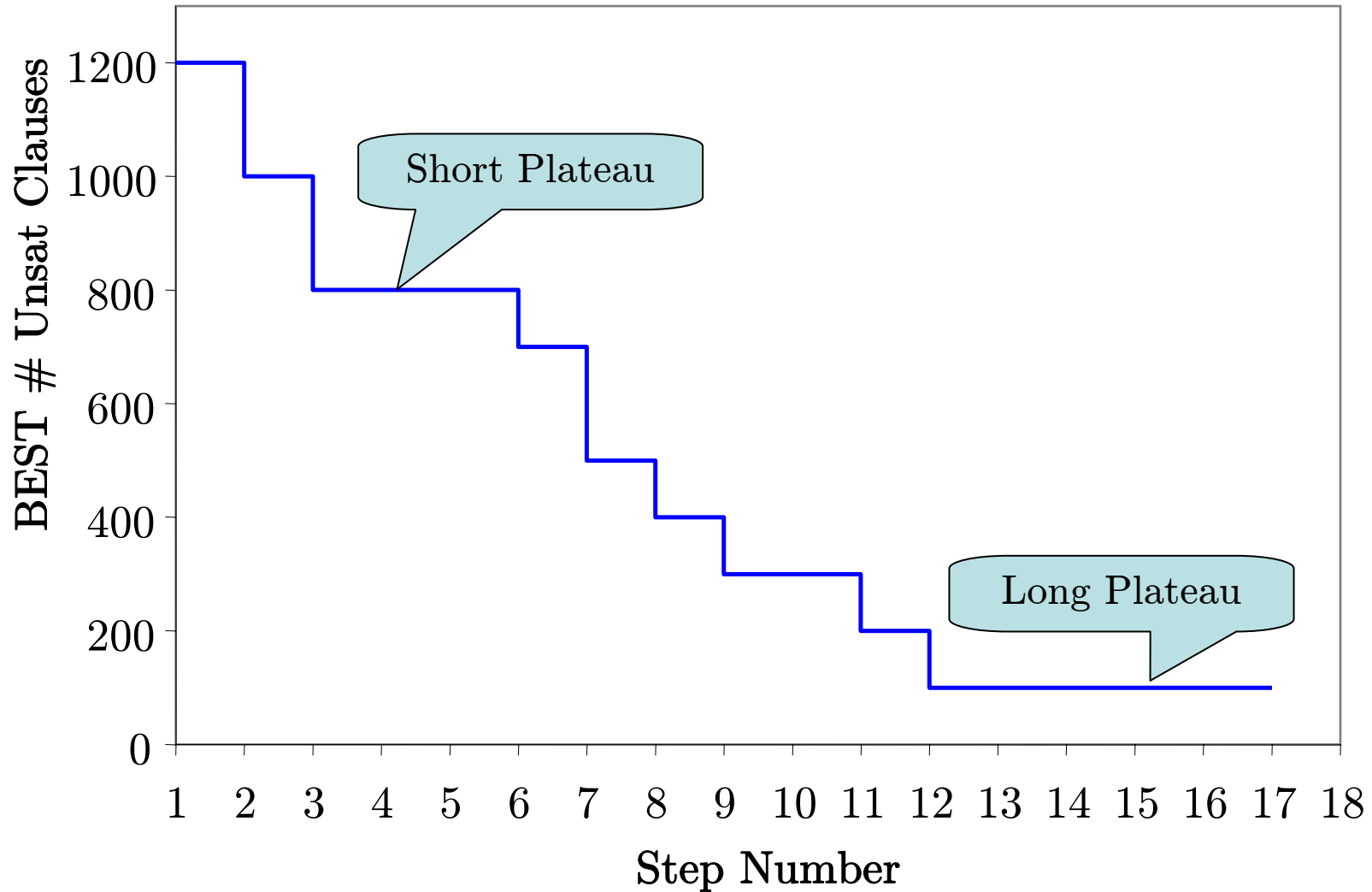
- Experimental Results

- Variable Size Data

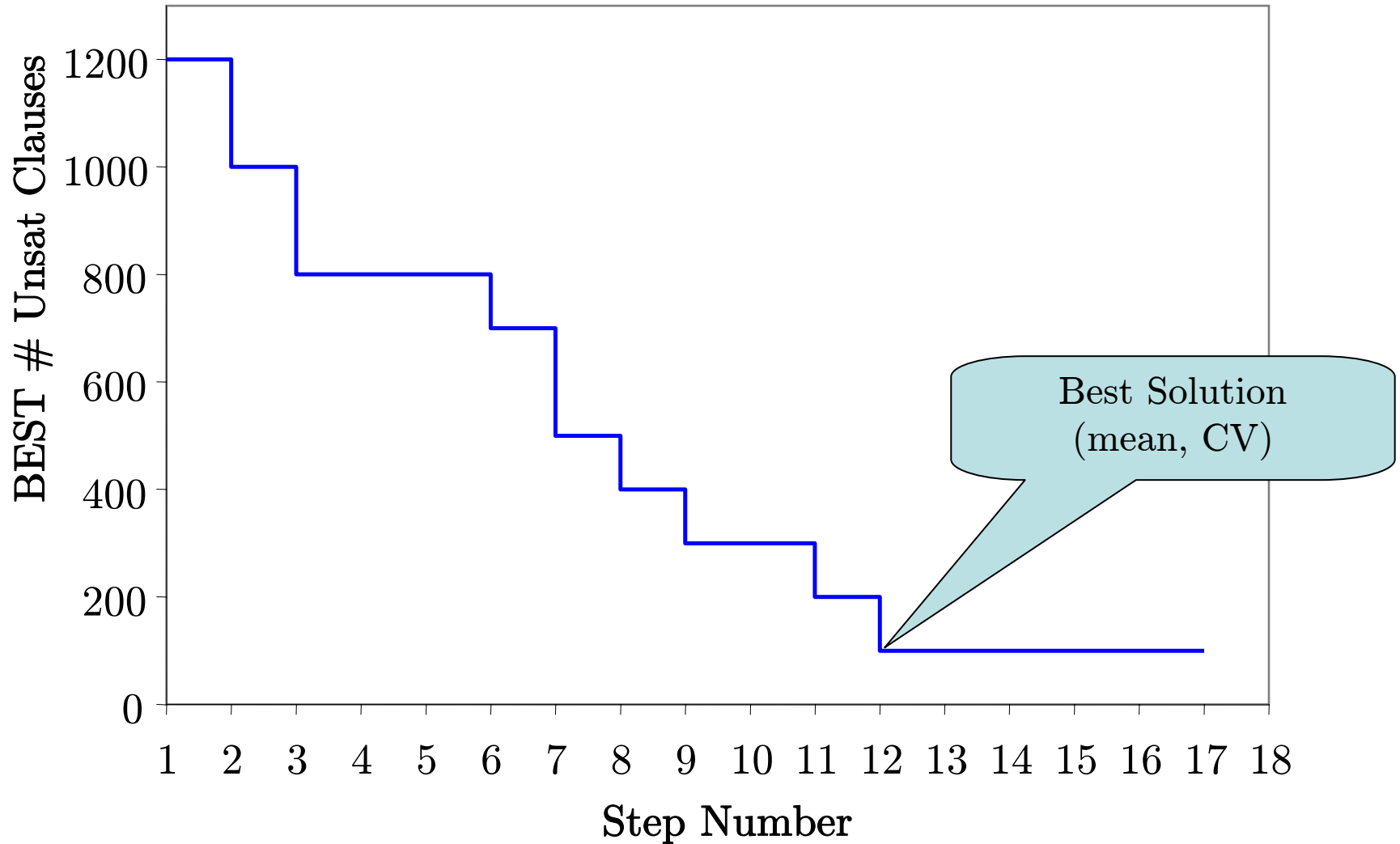
- Fixed Size Data



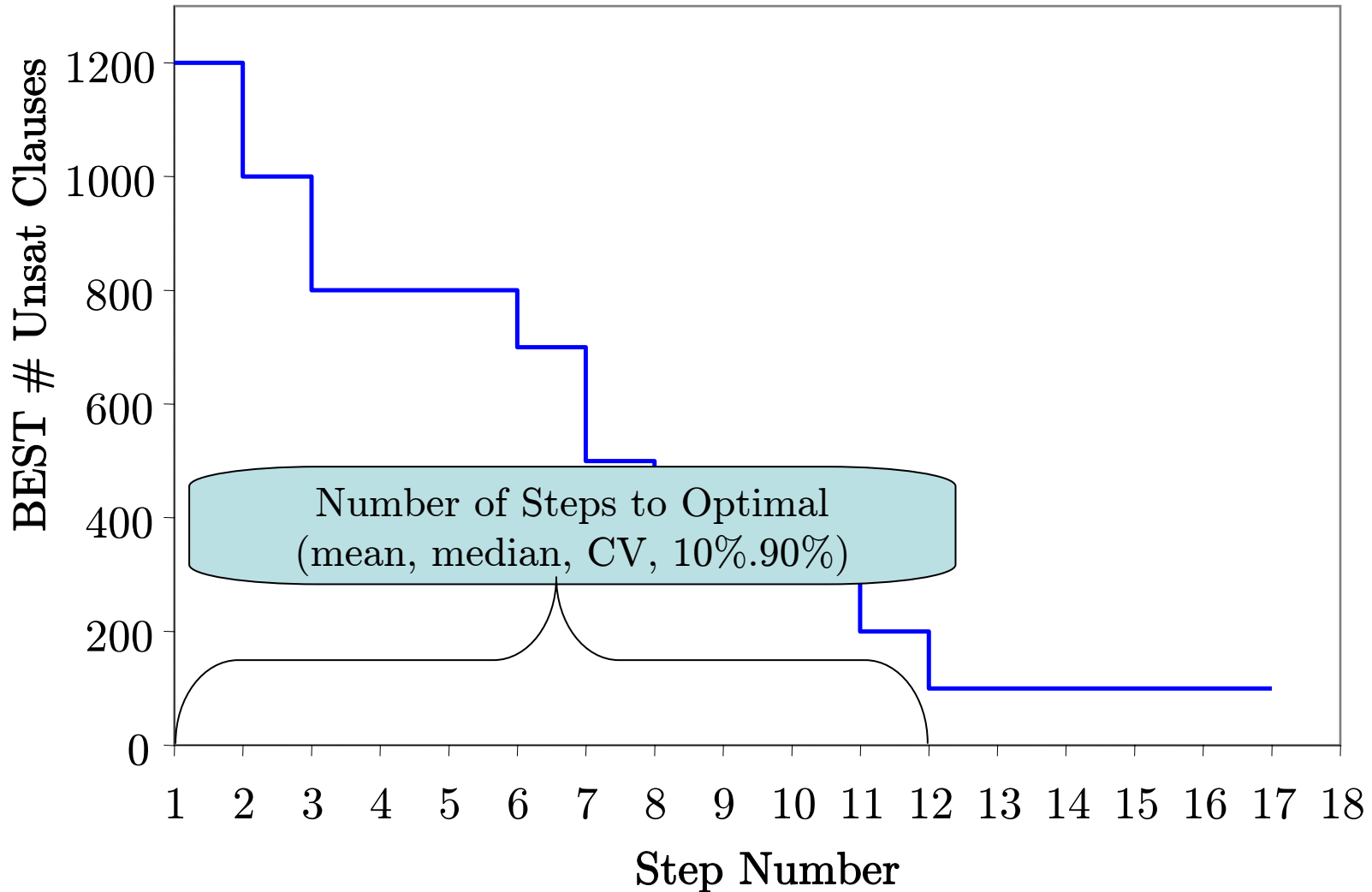
Features: Local Search Probing



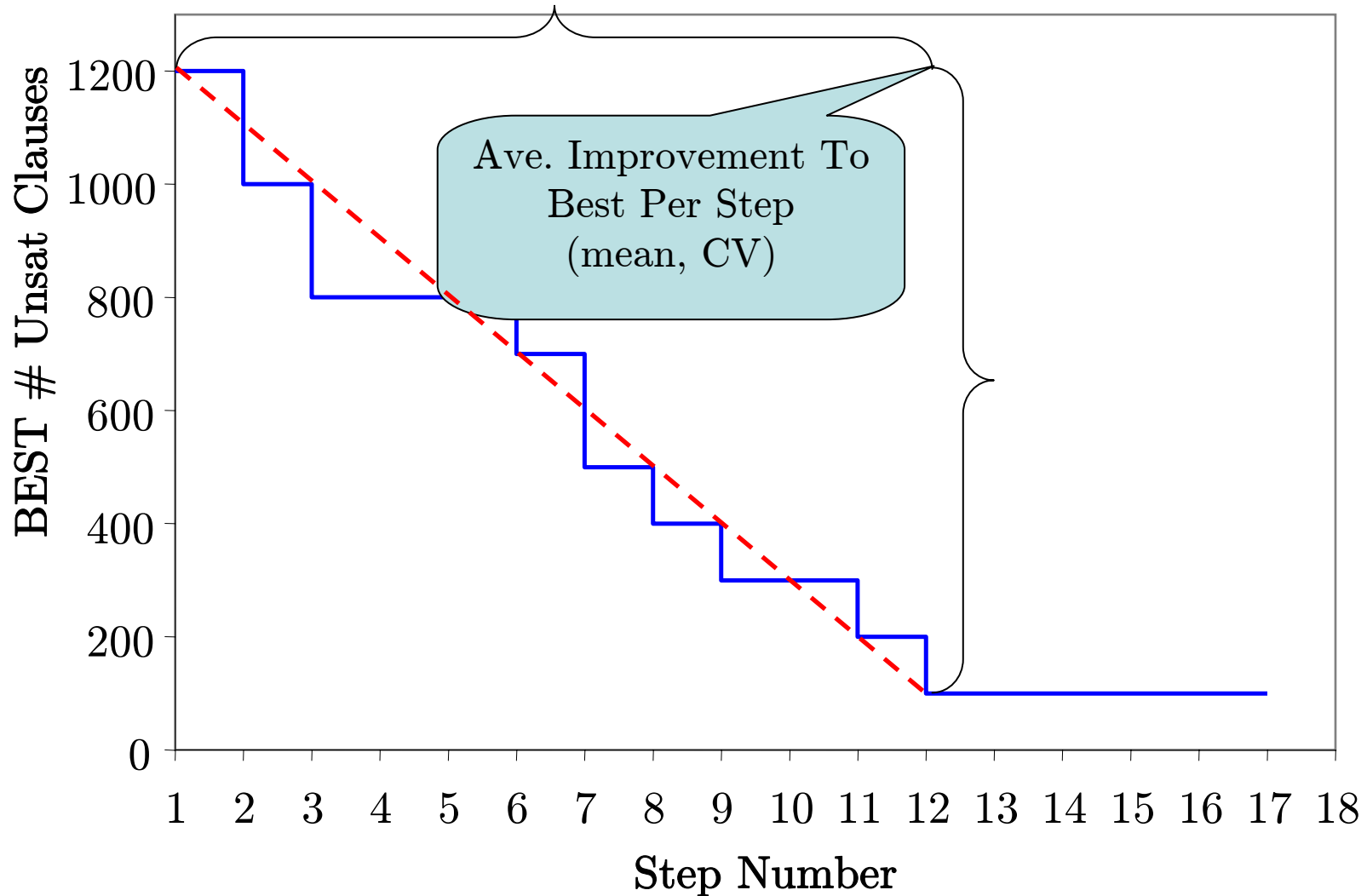
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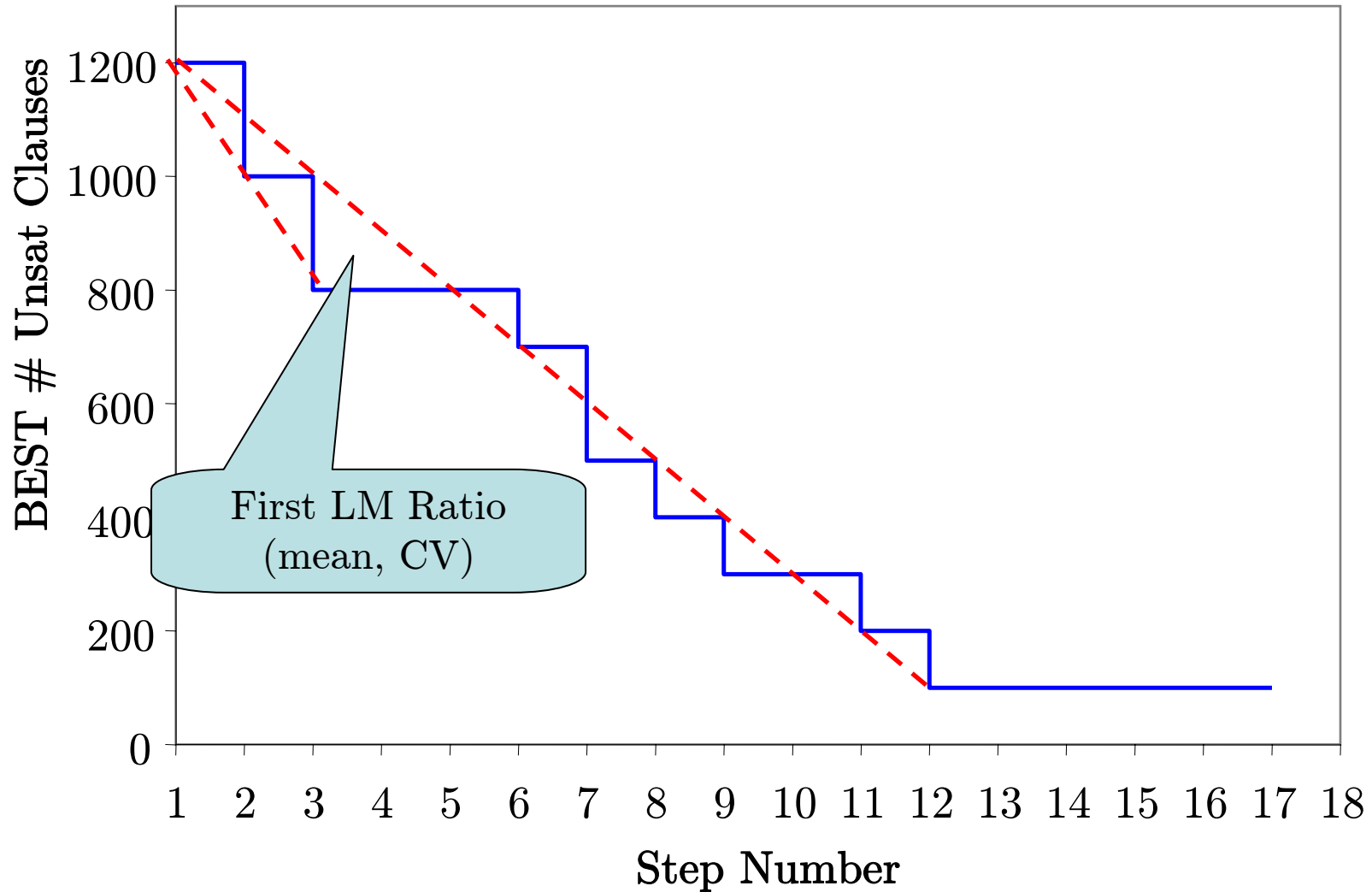
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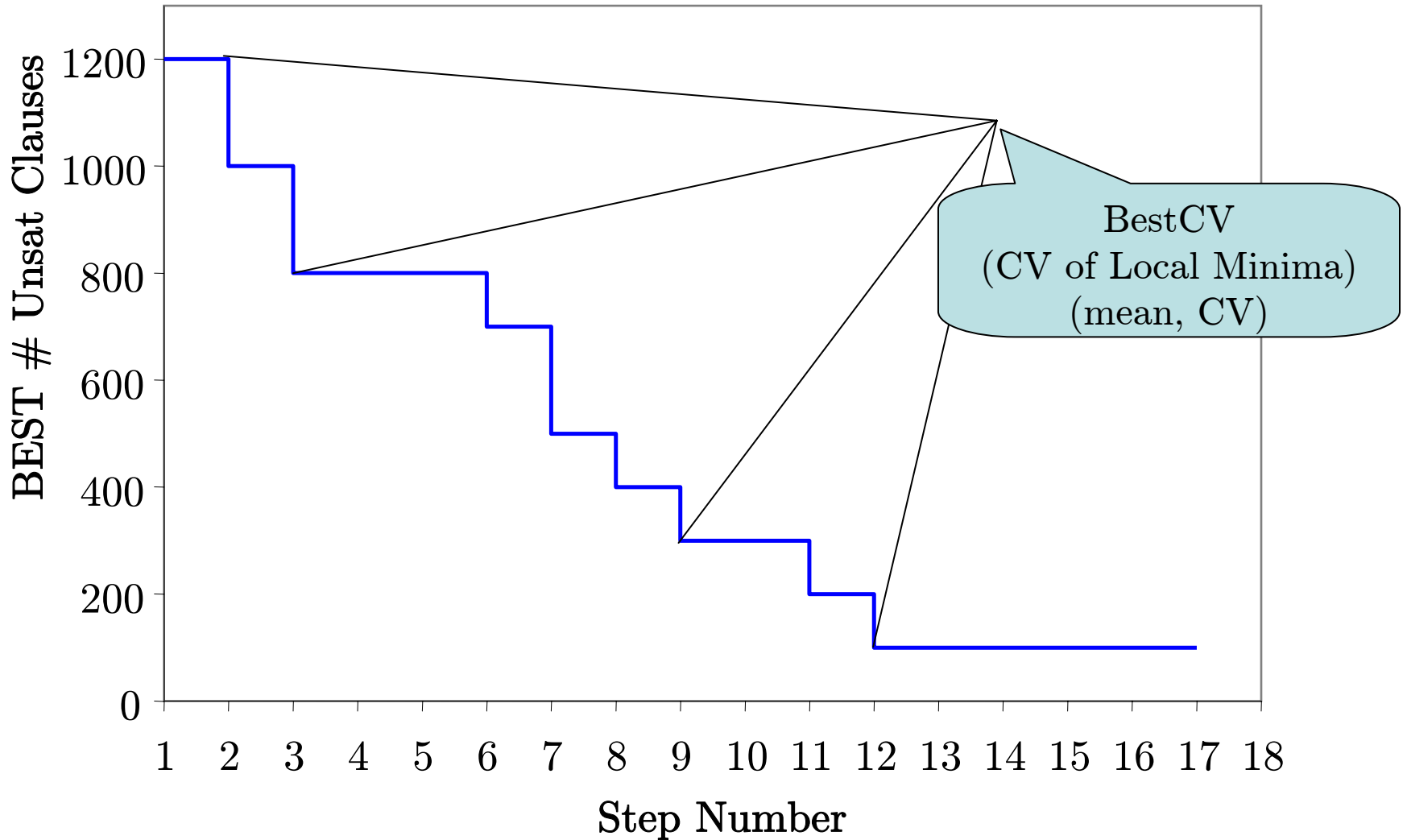
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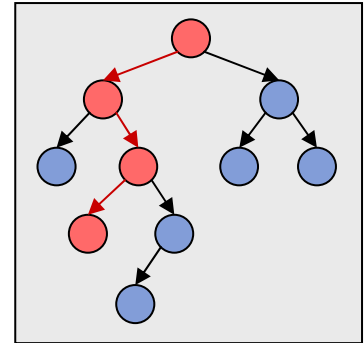


Features: Local Search Probing



Features: DPLL, LP

- **DPLL** search space size estimate
 - **Random probing** with unit propagation
 - Compute mean depth till contradiction
 - Estimate $\log(\#\text{nodes})$



- Cumulative number of **unit propagations** at different depths (DPLL with Satz heuristic)

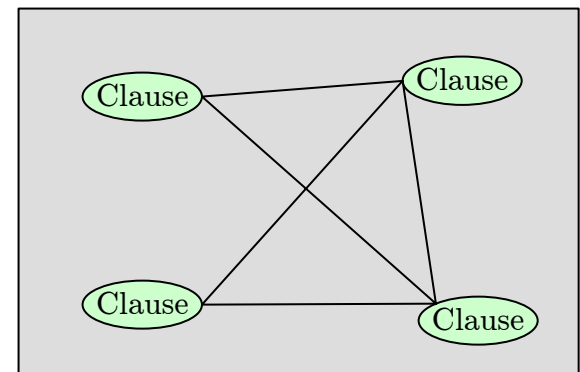
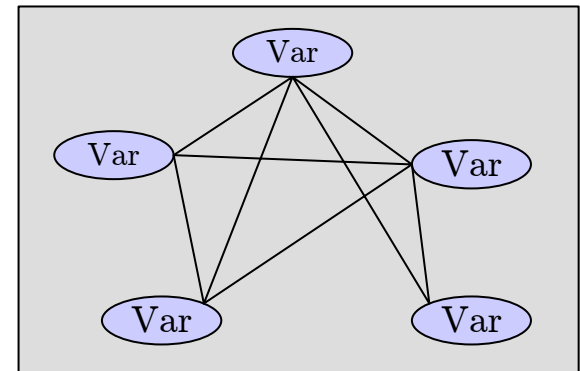
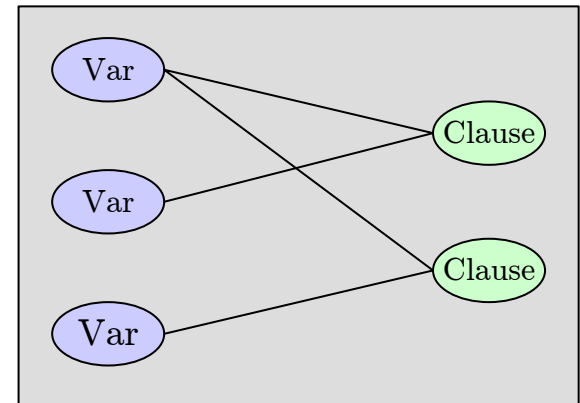
- **LP relaxation**

- Objective value
- stats of integer slacks
- #vars set to an integer

$$\begin{array}{ll} \text{maximize:} & \sum_{k \in C} \left(\sum_{i \in L, i \in k} v_i + \sum_{j \in \bar{L}, i \in k} (1 - v_j) \right) \\ \text{subject to:} & \sum_{i \in k, i \in L} v_i + \sum_{j \in k, j \in \bar{L}} (1 - v_j) \geq 1 \quad \forall k \in C \\ & v_i \in \{0, 1\} \quad \forall i \end{array}$$

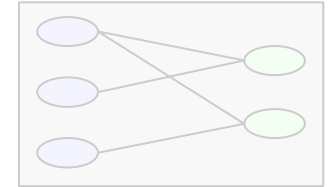
Other Features

- **Problem Size:**
 - v (#vars)
 - c (#clauses) } used for normalizing many other features
 - Powers of c/v , v/c , $|c/v - 4.26|$
- **Graphs:**
 - **Variable-Clause** (VCG, bipartite)
 - **Variable** (VG, edge whenever two variables occur in the same clause)
 - **Clause** (CG, edge iff two clauses share a variable with opposite sign)
- **Balance**
 - #pos vs. #neg literals
 - unary, binary, ternary clauses
- Proximity to **Horn formula**



Outline

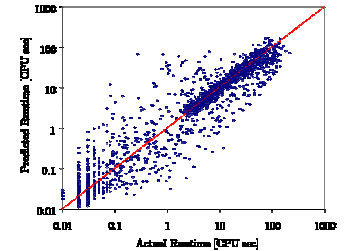
- Features



- Experimental Results

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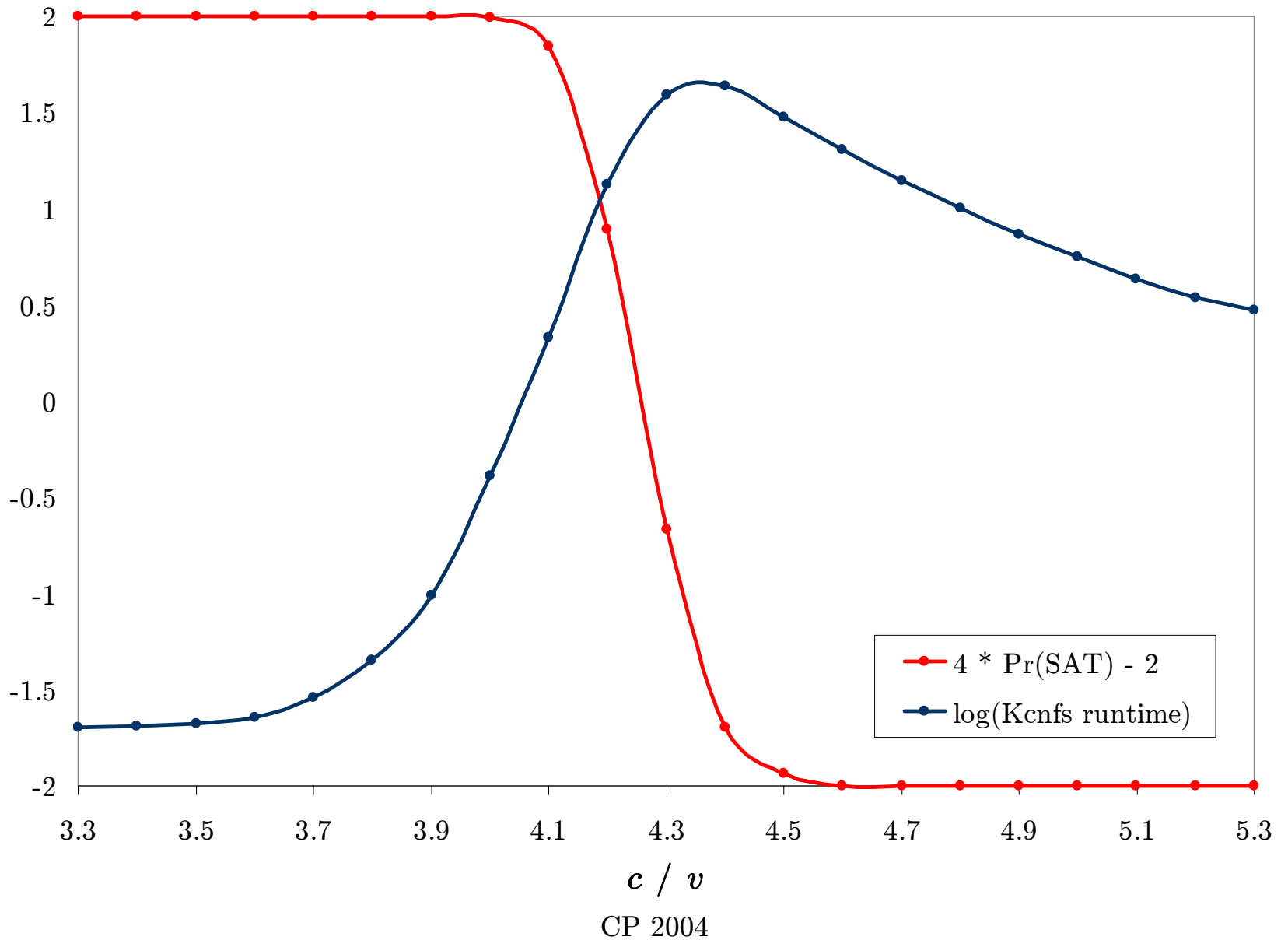
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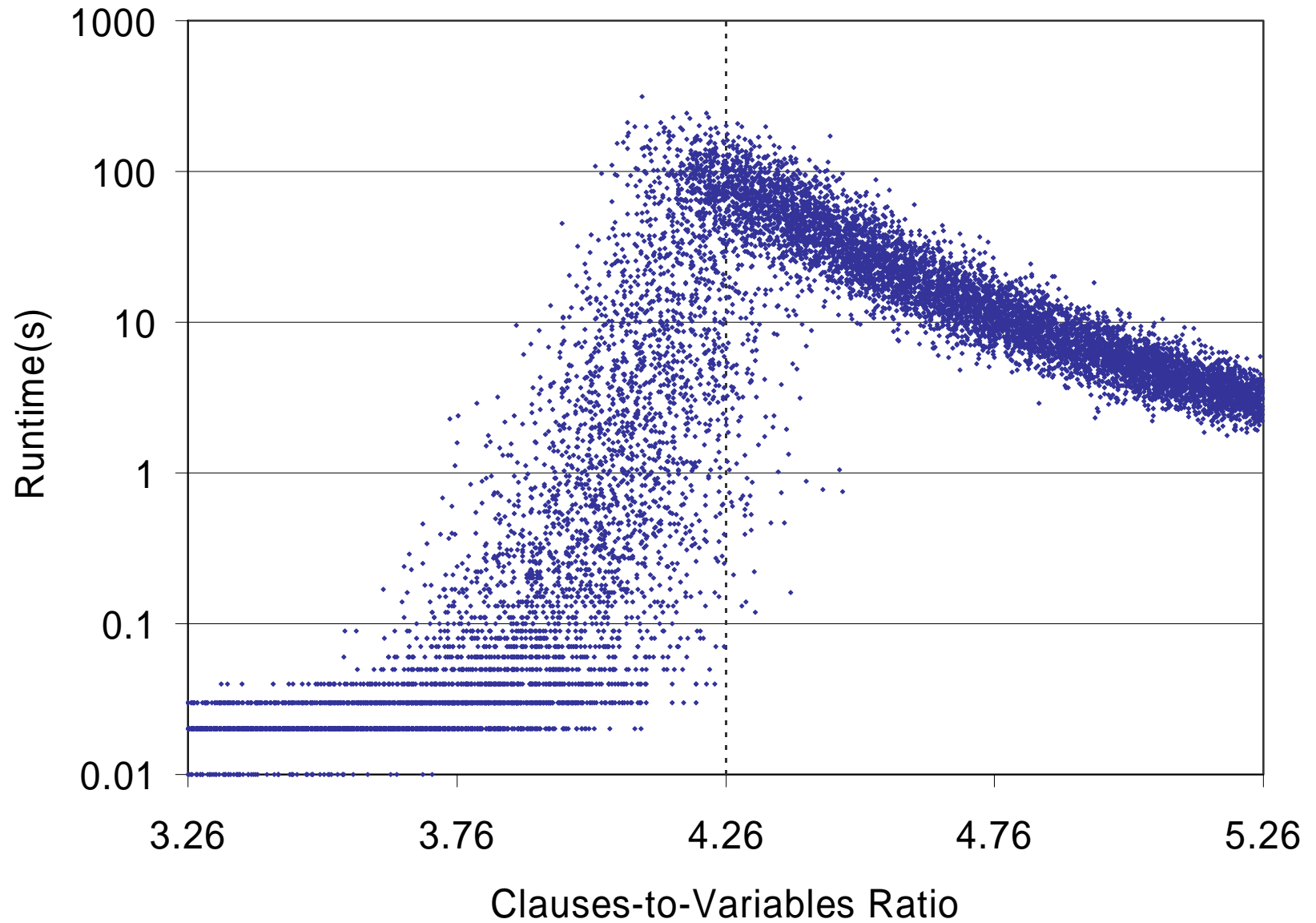
Experimental Setup

- Uniform random 3-SAT, 400 vars
- **Datasets** (20000 instances each)
 - **Variable-ratio** dataset (1 CPU-month)
 - c/v uniform in $[3.26, 5.26]$ ($\therefore c \in [1304, 2104]$)
 - **Fixed-ratio** dataset (4 CPU-months)
 - $c/v=4.26$ ($\therefore v=400, c=1704$)
- **Solvers**
 - Kcnfs [Dubois and Dequen]
 - OKsolver [Kullmann]
 - Satz [Chu Min Li]
- **Quadratic regression** with logistic response function
- Training : test : validation split – 70 : 15 : 15

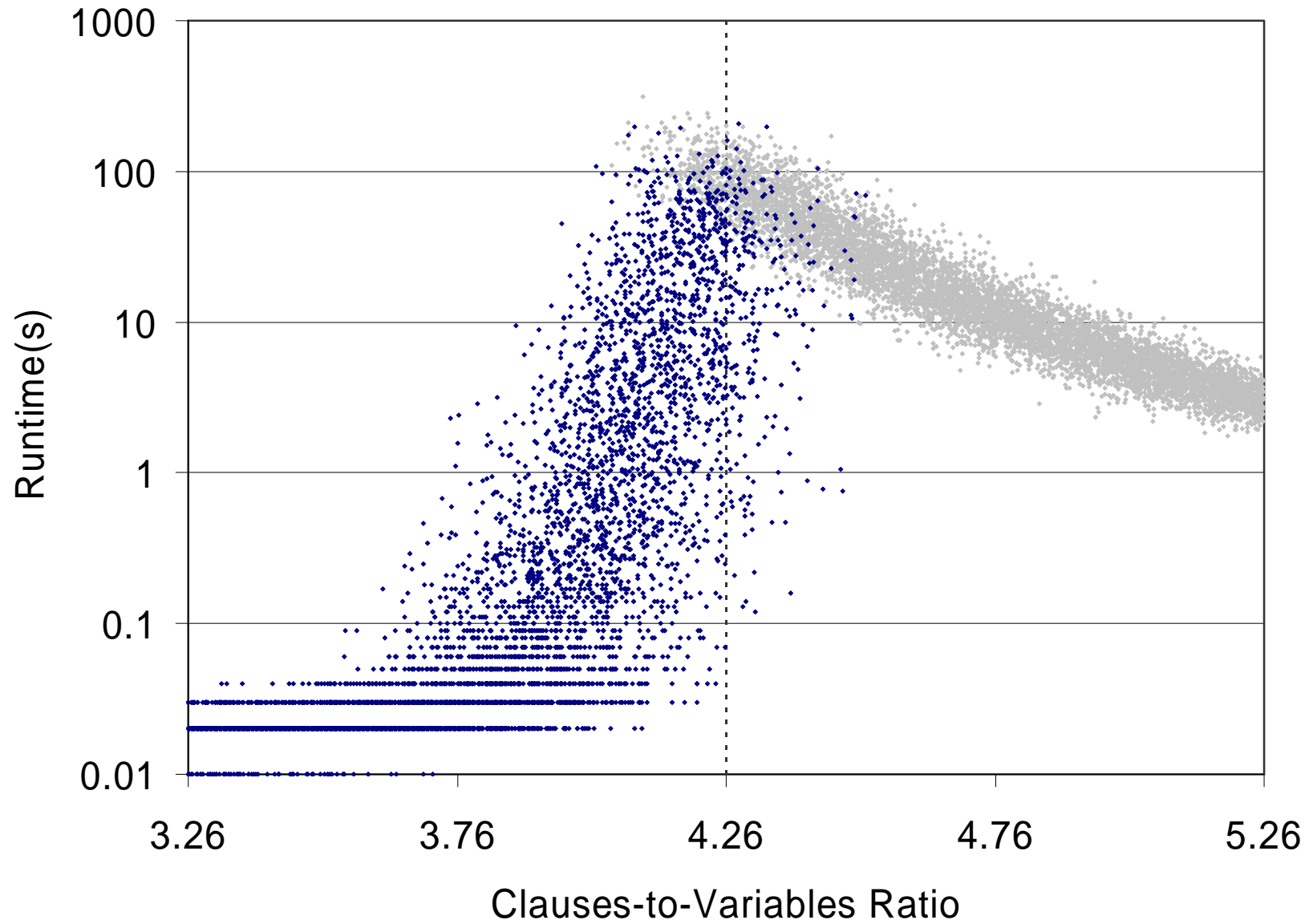
Kcnfs Data



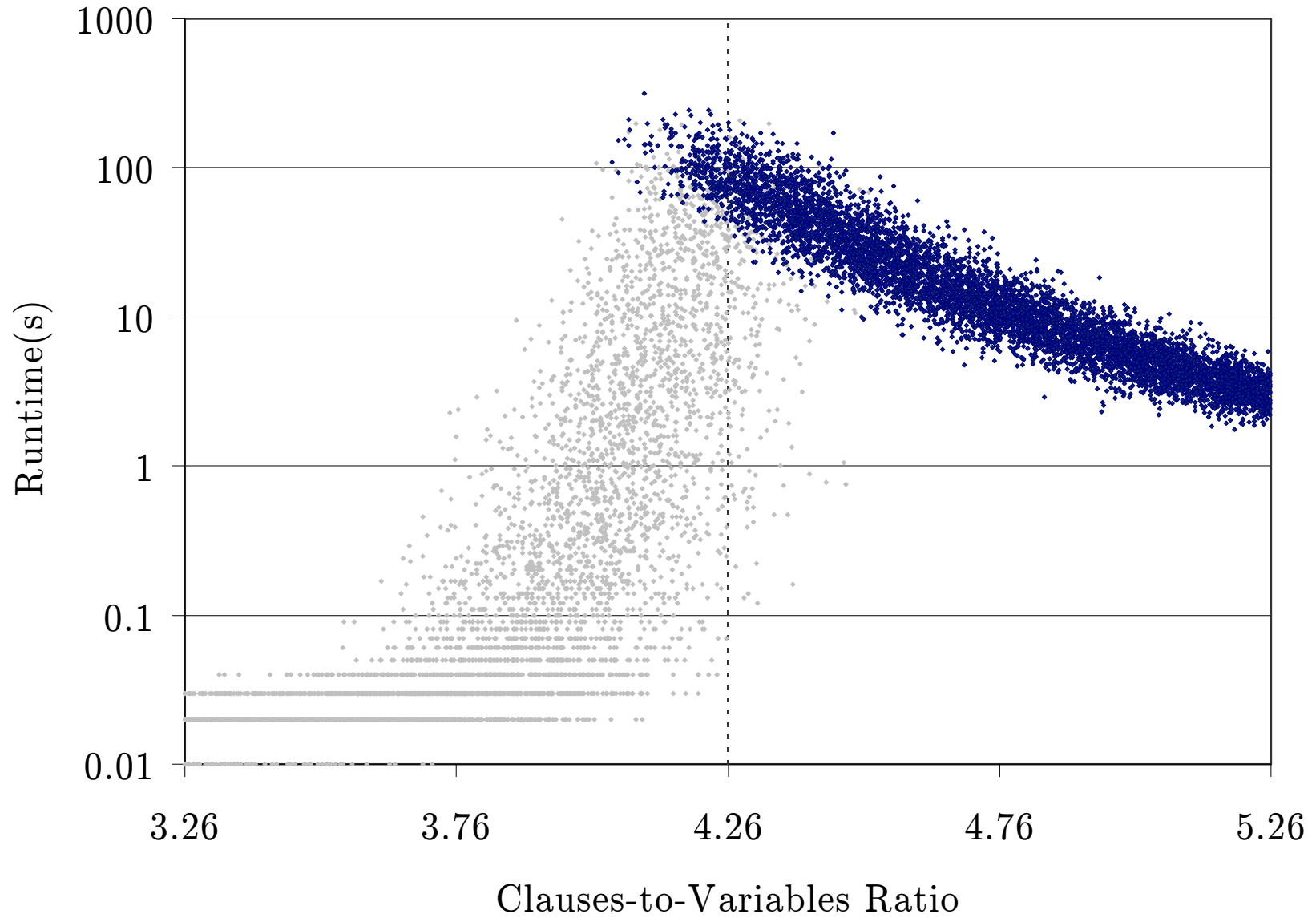
Kcnfs Data



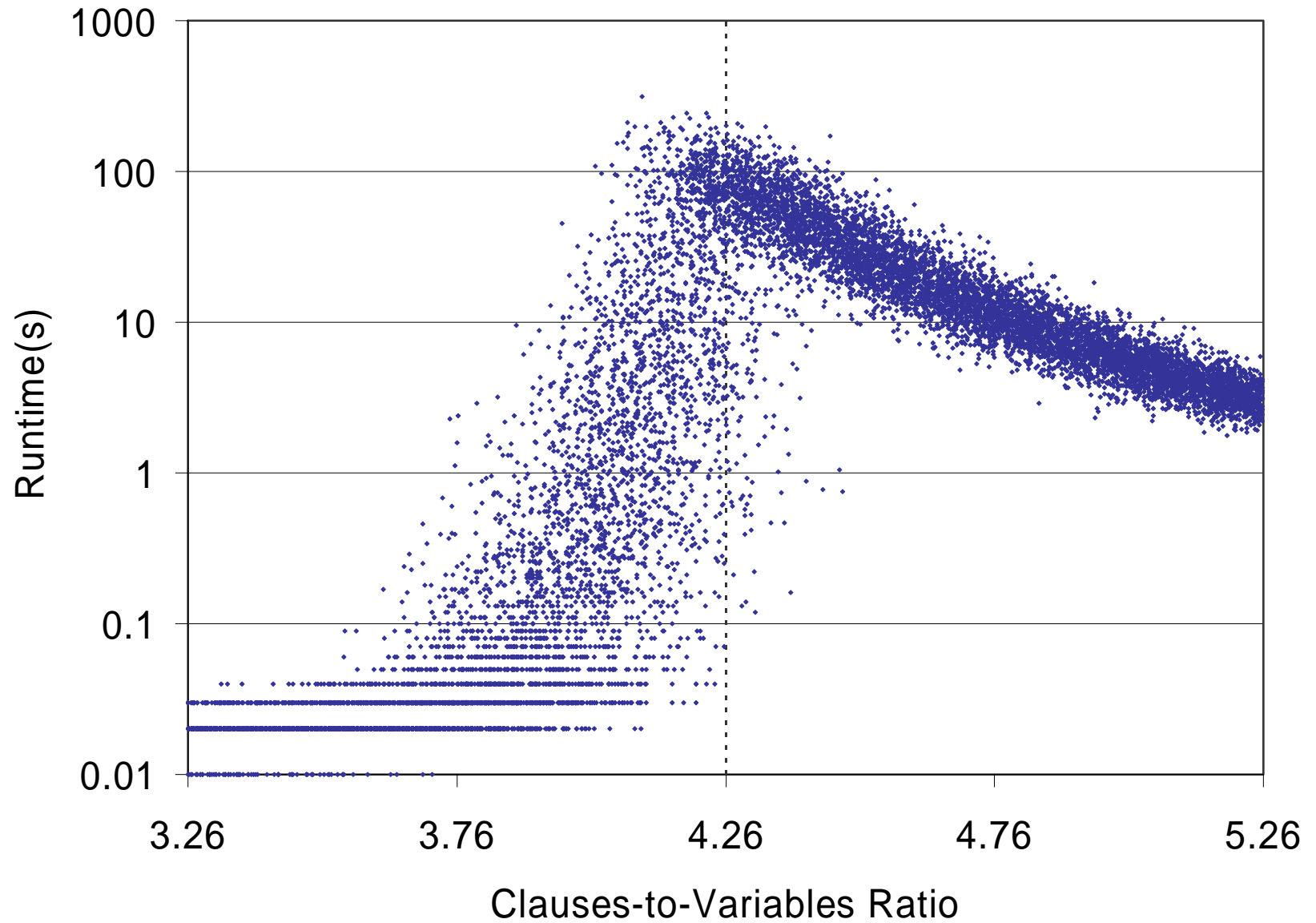
Kcnfs Data



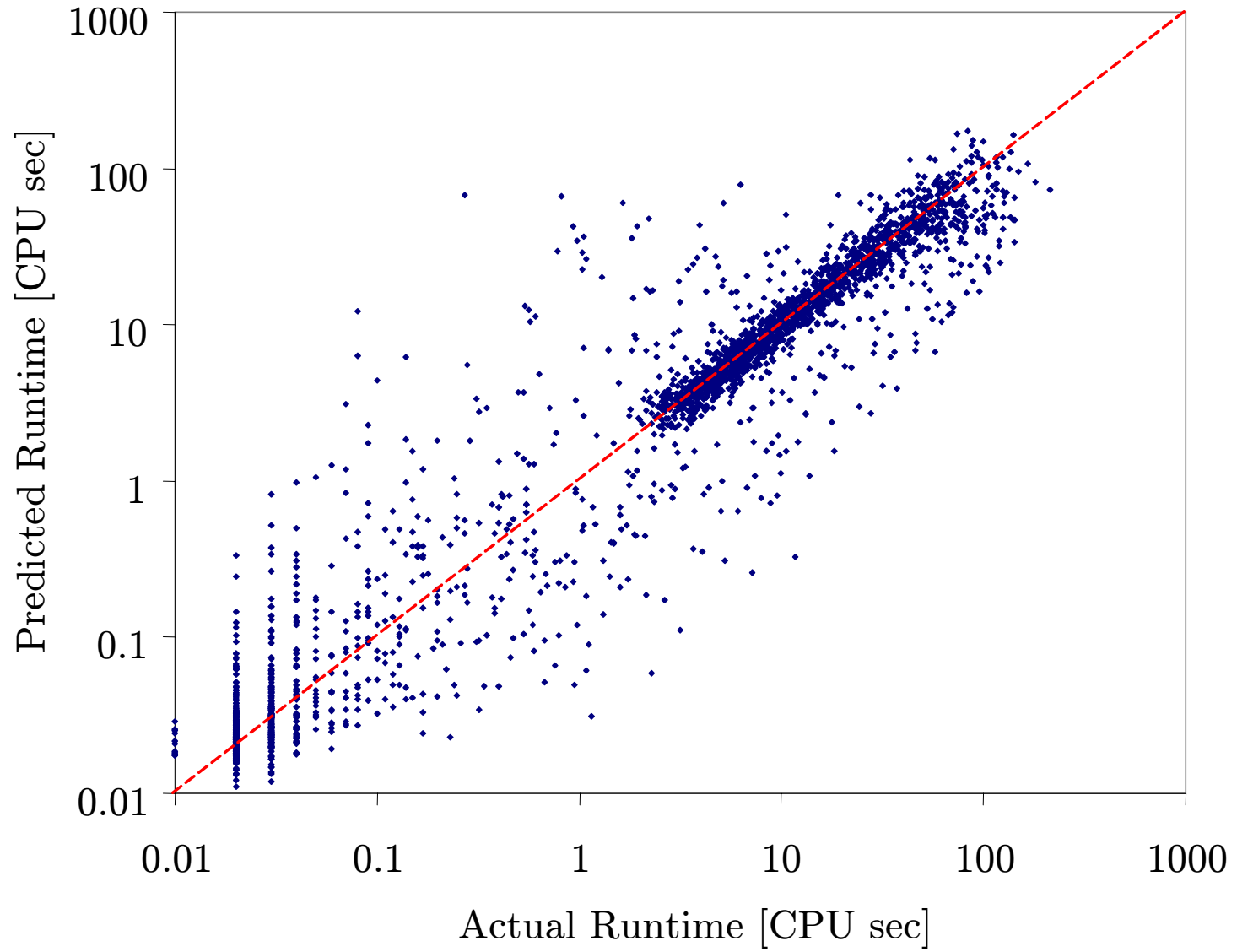
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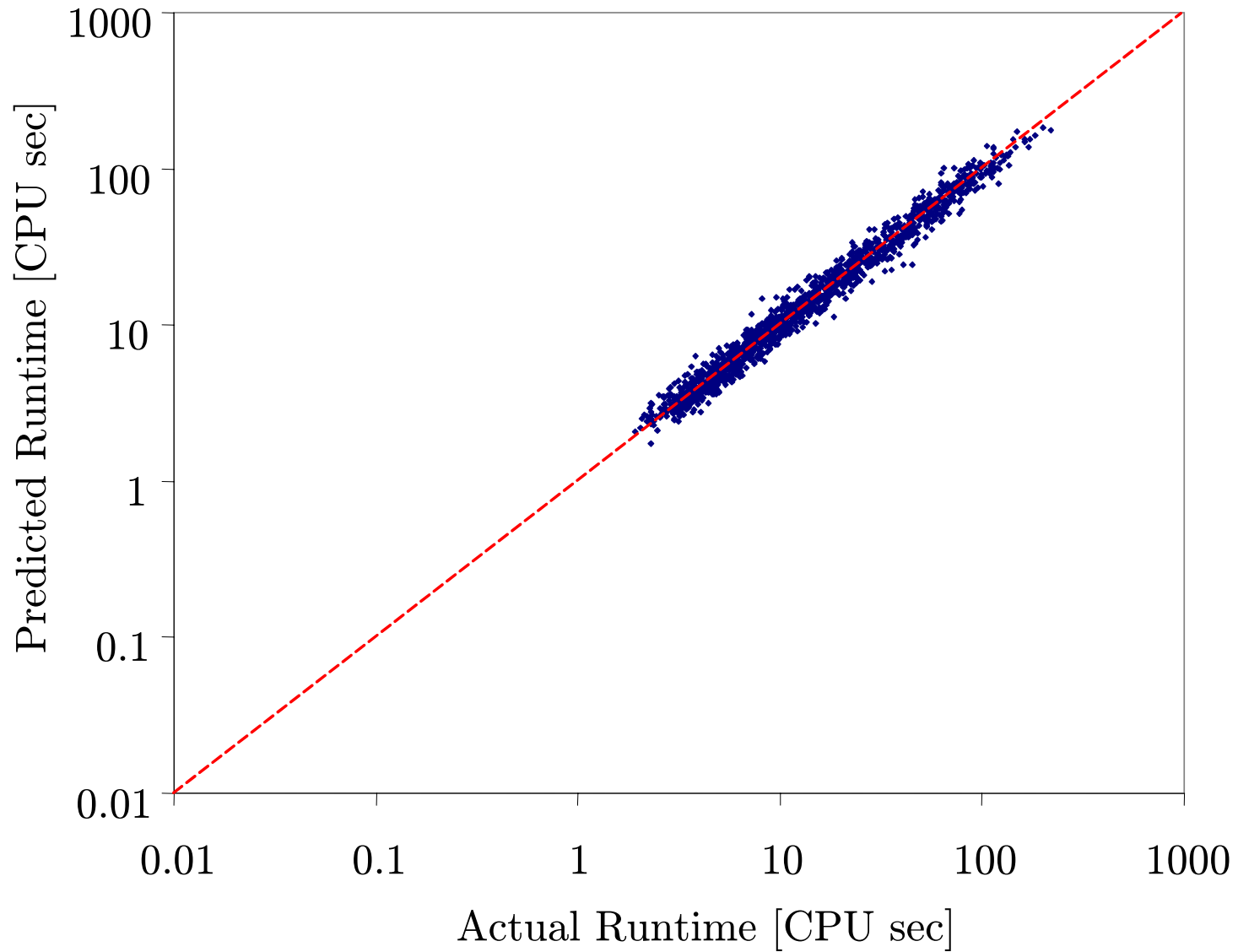
Kcnfs Data



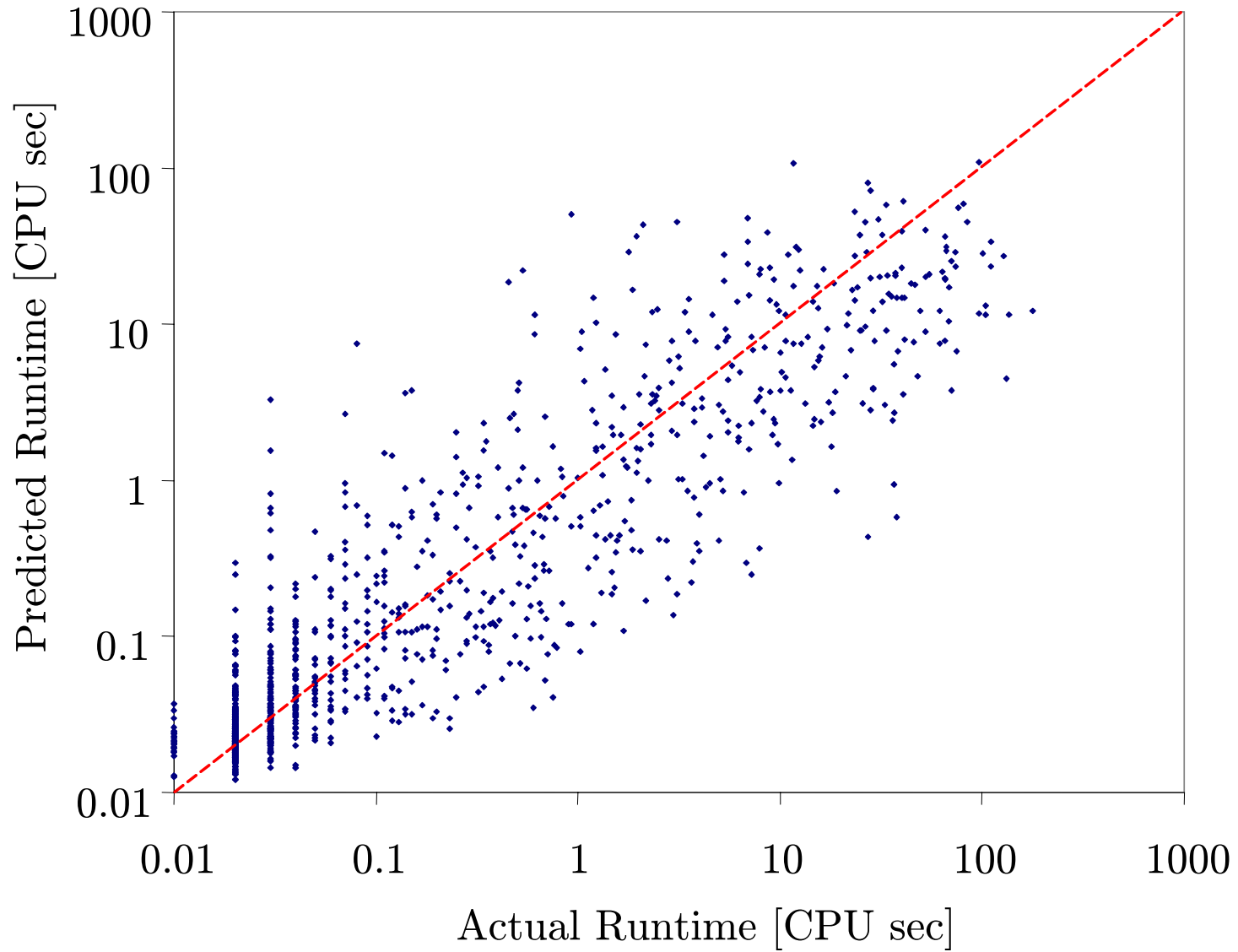
Variable Ratio Prediction (Kcnfs)



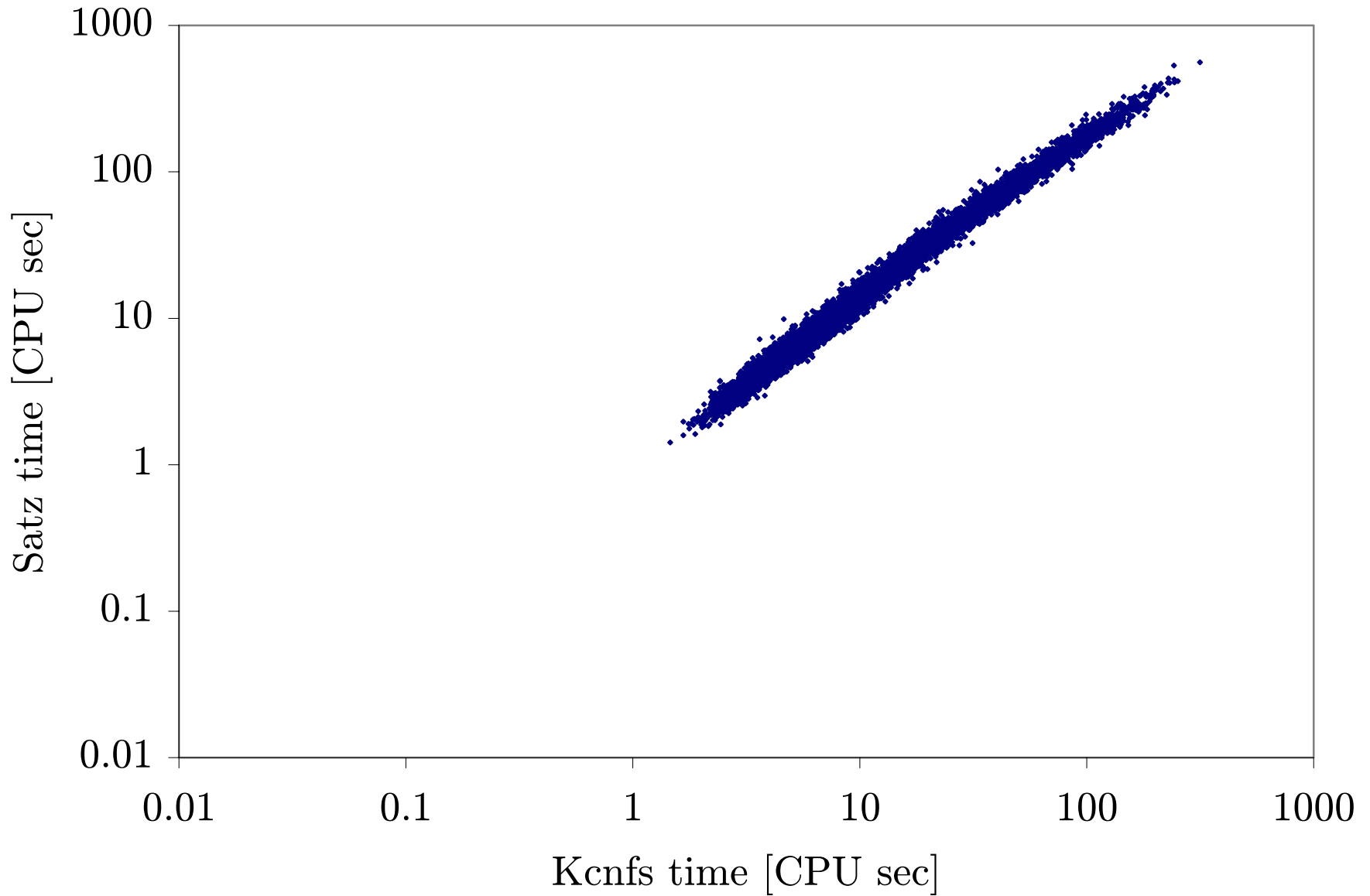
Variable Ratio - UNSAT



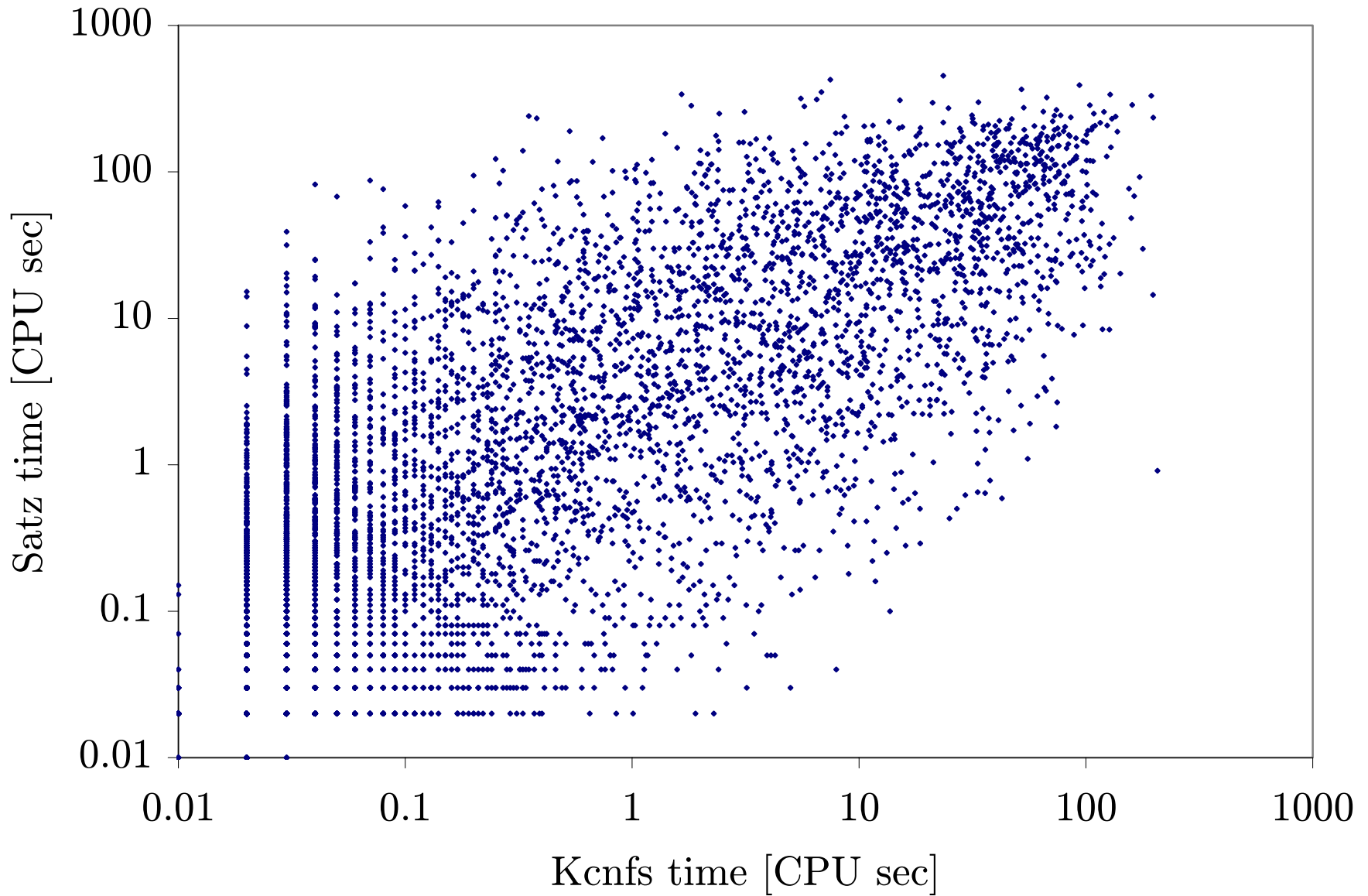
Variable Ratio - SAT



Kcnfs vs. Satz (UNSAT)



Kcnfs vs. Satz (SAT)



Feature Importance – Variable Ratio

- **Subset selection** can be used to identify features **sufficient** for approximating full model performance
- Other (correlated) sets could potentially achieve similar performance

Variable	Cost of Omission
$ c/v-4.26 $	100
$ c/v-4.26 ^2$	69
$(v/c)^2 \times SapsBestCVMean$	53
$ c/v-4.26 \times SapsBestCVMean$	33

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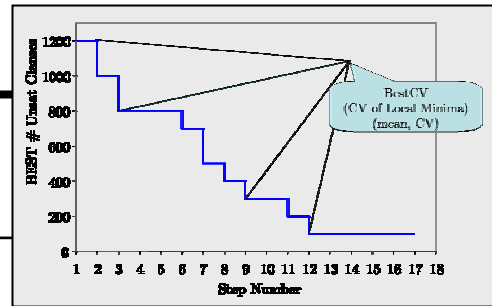
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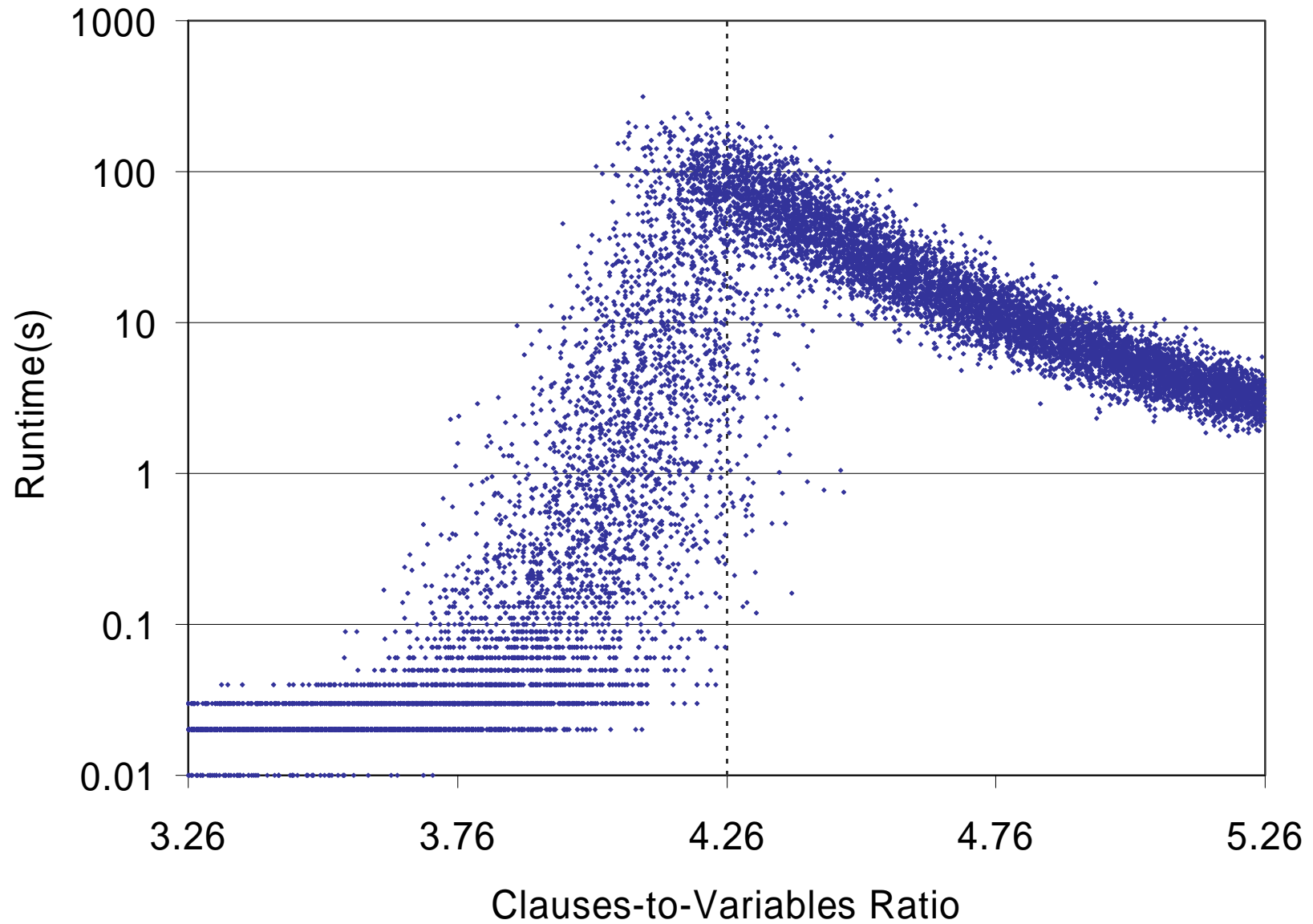
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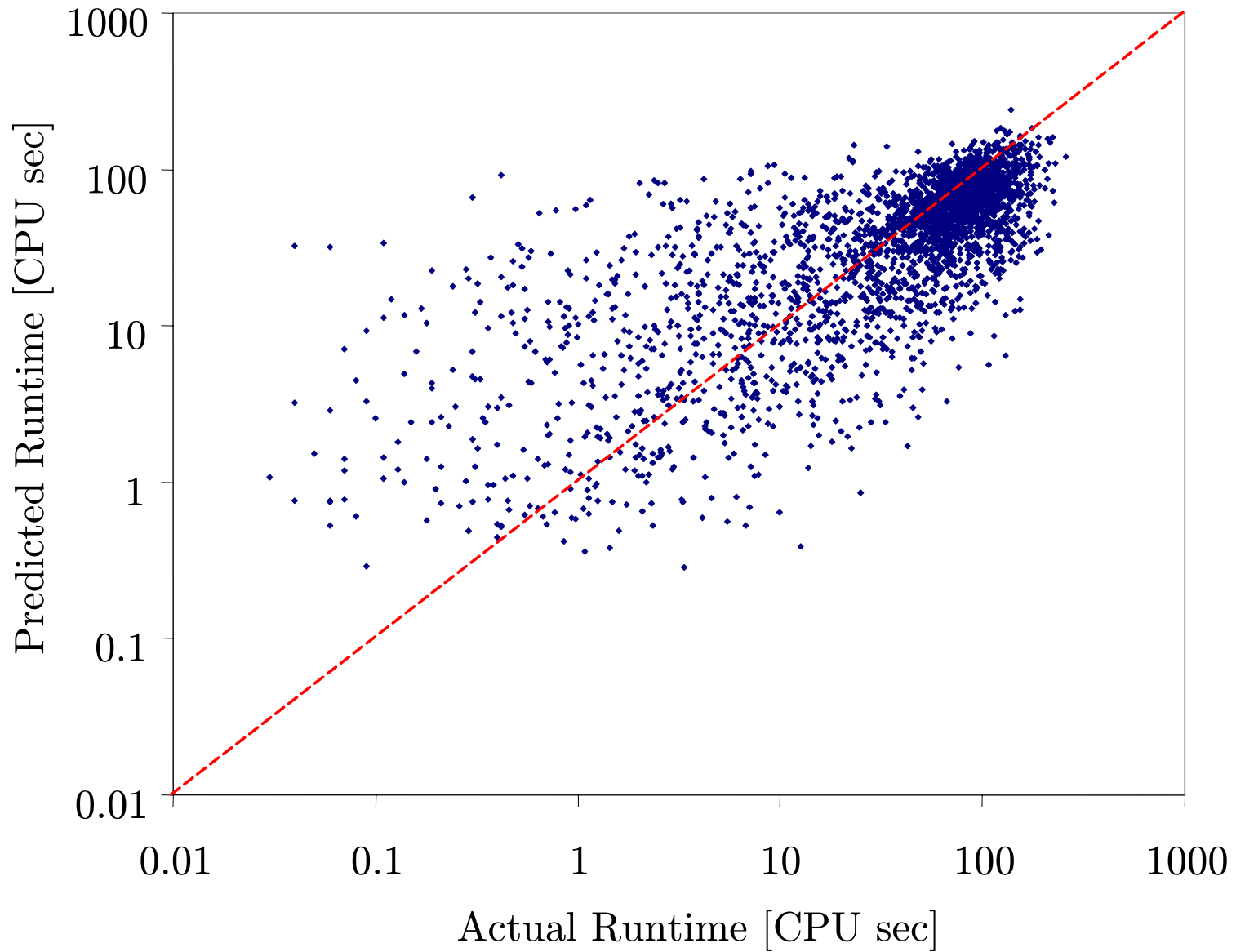
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Fixed Ratio Data



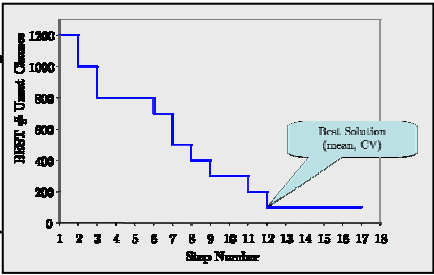
Fixed Ratio Prediction (Kcnfs)

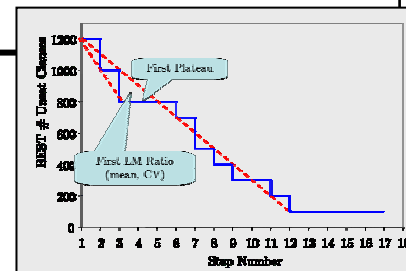


Feature Importance – Fixed Ratio

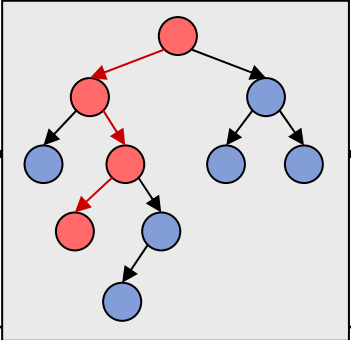
Variable	Cost of Omission
$SapsBestSolMean^2$	100
$SapsBestSolMean \times MeanDPLLDepth$	74
$GsatBestSolCV \times MeanDPLLDepth$	21
$VCGClauseMean \times GsatFirstLMRatioMean$	9

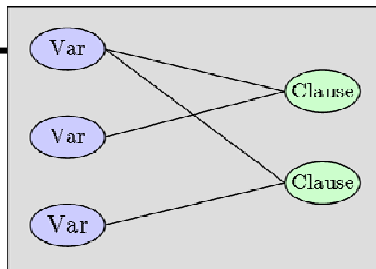
Feature Importance – Fixed Ratio

Variable	Cost of Omission
 <p><i>SapsBestSolMean²</i></p>	100
<p><i>SapsBestSolMean</i> × <i>MeanDPLLDepth</i></p>	74
<p><i>GsatBestSolCV</i> × <i>MeanDPLLDepth</i></p>	21
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Feature Importance – Fixed Ratio

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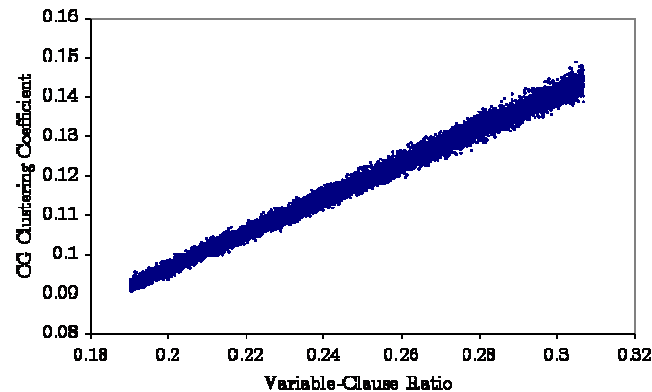


SAT vs. UNSAT

- **Training models separately** for SAT and UNSAT instances:
 - good models require **fewer features**
 - model **accuracy improves**
 - *c/v* no longer an important feature for VR data
 - Completely **different features** are useful for SAT than for UNSAT
- Feature importance on **SAT** instances:
 - **Local Search** features sufficient
 - 7 features for good VR model
 - 1 feature for good FR model (SAPSBestSolCV x SAPSAveImpMean)
 - If LS features omitted, **LP + DPLL search space** probing
- Feature importance on **UNSAT** instances:
 - **DPLL search space** probing
 - **Clause graph** features

Beyond Ratio: Weighted CG Clustering Coefficient

- Byproduct of our analysis: a very **strong correlation** between weighted CG clustering coefficient and v/c



- Clustering coefficient is a more fundamental concept than v/c , since it describes the **structure of the constraints** explicitly, not implicitly.
 - correlation between (unweighted) CC and hardness has been shown for **other constraint problems** (e.g., graph coloring, combinatorial auctions)
- We have a **proof sketch** of this correlation

Conclusions

- Can construct **good models** for DPLL solvers
- These models can be **analyzed** to gain understanding about what makes instances hard or easy for solvers
- **Algorithm portfolios** can be constructed (**Satzilla**)
- More specifically:
 - Strong relationship between **LS and DPLL** search spaces
 - Our approach **automatically identified** importance of c/v
 - **SAT/UNSAT instances** have very different performance characteristics; it helps to model them separately
 - **Clustering Coefficient** explains why c/v is important in terms of local properties of constraint graph